

## DS8000 Replication Performance Considerations

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#### Agenda

#### E Actions 11.1 **Replication Review** Multiple Incremental FlashCopy Multi-Target PPRC Performance • **PPRC** Synchronization • **Global Copy Collision Enhancement** zHyperWrite © Workload Based z/OS Global Mirror (XRC) Write Pacing Easy Tier Heat Map Transfer



#### **DS8000** Replication Review



<b>FlashCopy</b>	Metro Mirror		Global Mirror		<u>Metro Global Mirror</u> Metro z/OS Global Mirror	
Point in Time	Synchronous		z/OS Global Mirror		<u>Nietro z/US</u>	<u>Giodal Mirror</u>
Сору	Mirroring		Asynchronous Mirroring		Three site and Four Site Synchronous & Asynchronous Mirroring	
Within the same Storage System	Primary Site A	Metro distance Site B	Primary Site A	Out of Region Site B	Primary Site A	Out of Region Site C/D
	Unit leaves		The grant weight		Met Site	
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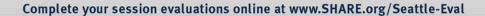
# Multiple Incremental FlashCopy

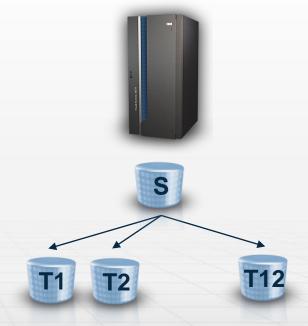




#### **Multiple Incremental FlashCopy**

- Previously only a single incremental FlashCopy was allowed for any individual volume
- This provides the capability for up to 12 incremental FlashCopies for any volume
- A significant number of clients take two (or more) FlashCopies per day for database backup both of which can now be incremental
- The Global Mirror journal FlashCopy also counts as an incremental FlashCopy so the testing copy can now also be incremental
- The functionality is also available as an RPQ from R7.1.5







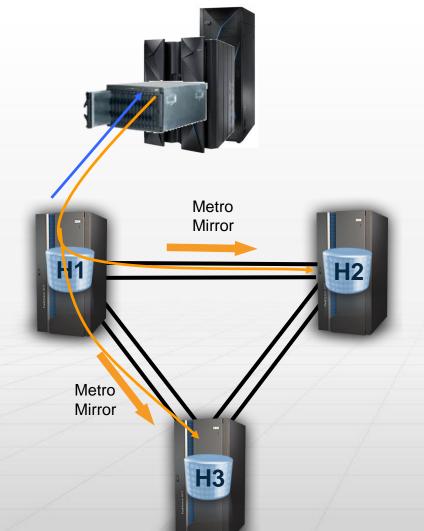


# MultiTarget Metro Mirror Performance





### **Multi-Target Metro Mirror**



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- Allow a single volumes to be the source for more than one PPRC relationship
- Provide incremental resynchronization functionality between target devices
  - Use cases include
    - Synchronous replication within a datacentre combined with another metro distance synchronous relationship
    - Add another synchronous replication for migration without interrupting existing replication
    - Allow multi-target Metro Global Mirror as well as cascading for greater flexibility and simplified operational scenarios
      - Combine with cascading relationships for 4-site topologies and migration scenarios

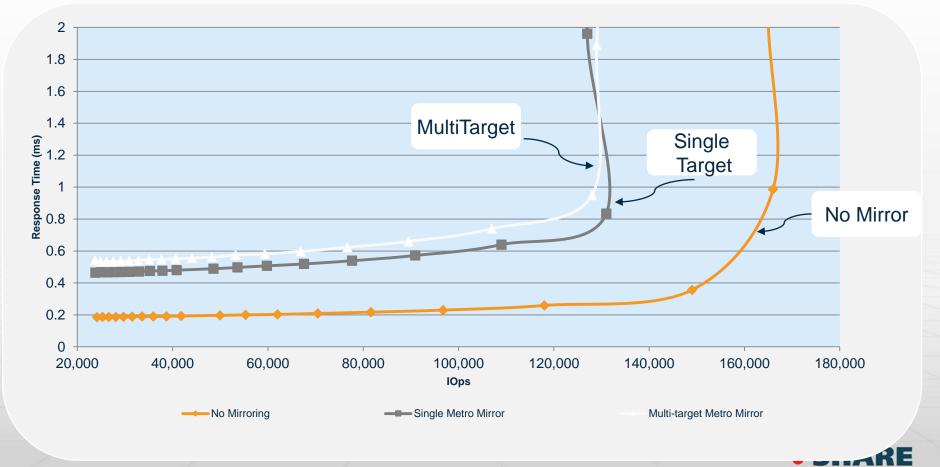


#### MultiTarget Metro Mirror Performance



in Seattle 20

4KB Writes



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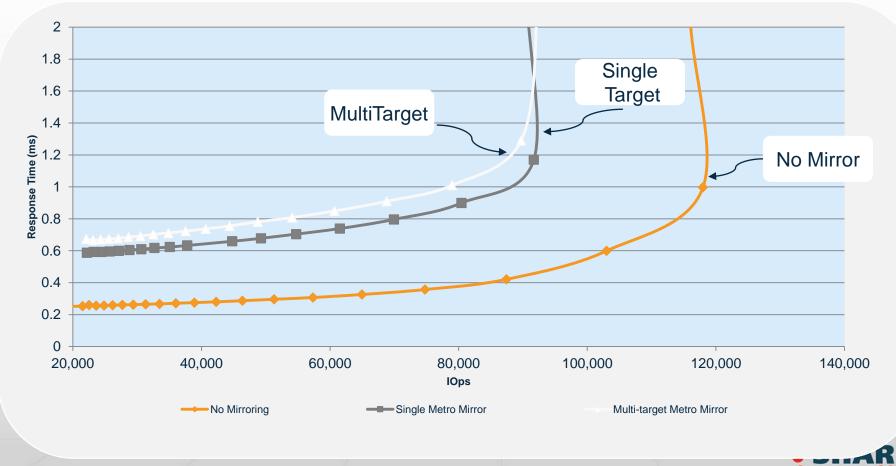
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#### MultiTarget Metro Mirror Performance



in Seattle 2

#### 27KB Writes



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# **PPRC Synchronization**





### **PPRC Synchronization**

- The asynchronous copying of data from a PPRC primary to a secondary.
- Copies data that is out-of-sync between primary and secondary
  - Initial copy when a pair is established or resumed
  - Global Copy / Global Mirror to asynchronously transfer updated data



H1





#### Pre-7.4 Design

- Volume based
  - When a volume spans ranks, only the part on one rank copied at a time
- Did not scale with volume size
  Resources allocated per volume, regardless of size
- No priority mechanism
- Unable to handle multiple relationships on a volume for MultiTarget PPRC



#### **Objectives**

- Support MultiTarget PPRC
- Finish the copy as quickly as possible
  - Fully utilize the PPRC links
- Minimize the impact on other work
  - Do not overdrive the ranks on the primary
  - Minimize impact on host I/O

#### Do the most important work first

#### Priority scheme

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H2

**H**1





#### **New Design**

- Balances workload across:
  - PPRC Ports
  - Extent Pools
  - Device Adapters
  - Ranks
- Assigns priorities

 For example, forming GM consistency groups > Resynchronization

Unit of work is an extent – Scales with volume size





# **Global Copy Collision Avoidance**



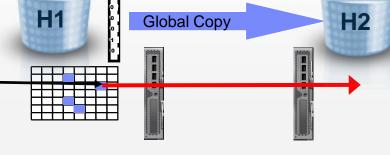
## **Global Copy Collision**

#### Collision definition:

- Track is locked for Global Copy to transfer it to the secondary
- Host write occurs for same track.

#### Result:

- Host write must wait for Global Copy transfer to complete
- Impact to application



Track in the process of being sent is locked to prevent writes from occurring



- Not usually a problem except for situations with
  - Have unstable networks
  - Have high latency / long distance networks
  - Have workloads with a high rate of data rereference (e.g. logging)
  - Have very latency sensitive applications

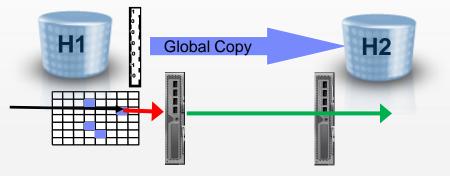
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## **Global Copy Collision Avoidance**

- Global Copy releases track lock after transfer of data to local host adapter
- Allows Host Write to access track immediately without waiting for Global Copy transfer to complete
- Global Copy detects when track has been modified by another host write
  - Available with R7.4 and as RPQ on R7.2 and R6.3







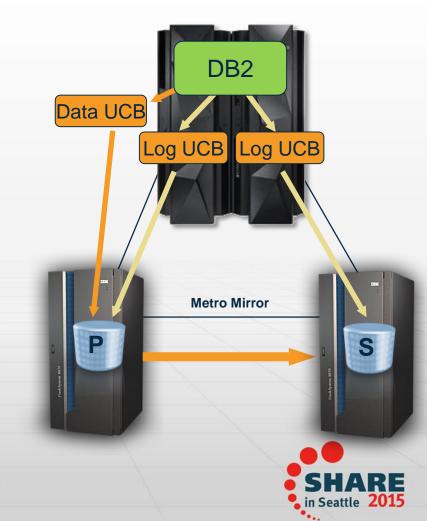
# IBM zHyperWrite





#### **zHyperWrite**

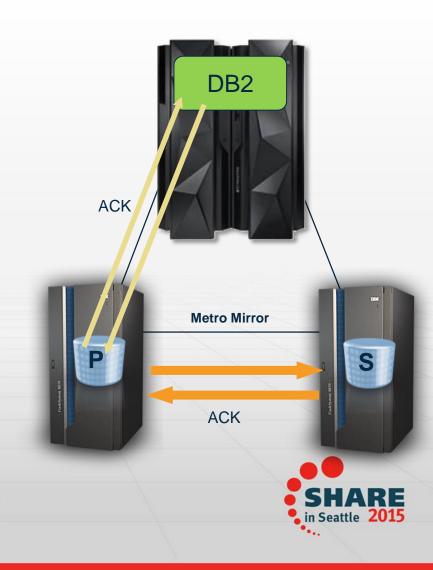
- Improved DB2 Log Write Performance with DS8870 Metro Mirror
  - Reduces latency overhead compared to normal storage based synchronous mirroring
- Reduced write latency and improved log throughput





## **DB2 Log Write with Metro Mirror**

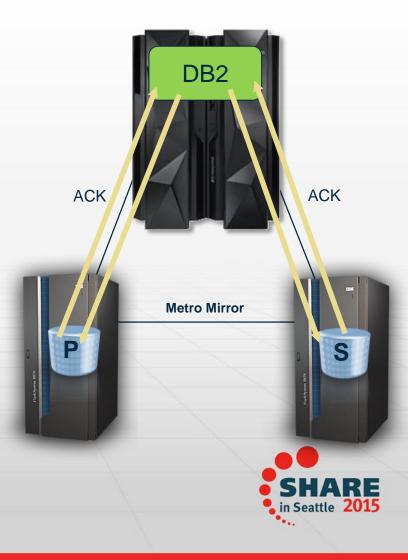
- 1. DB2 Log Write to Metro Mirror Primary
- 2. Write Mirrored to Secondary
- 3. Write Acknowledged to Primary
- 4. Write Acknowledged to DB2





#### Write with zHyperWrite

- 1. DB2 Log Write to Metro Mirror Primary and Secondary in parallel
- 2. Writes Acknowledged to DB2
- 3. Metro Mirror does <u>not</u> mirror the data.

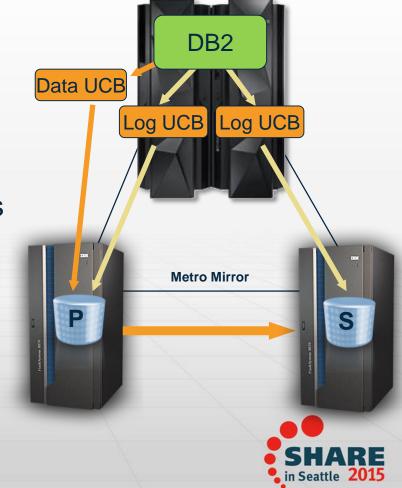




#### IBM zHyperWrite

- Supports HyperSwap with TPC-R or GDPS
- Enabled through

- SYS1.PARMLIB(IECIOSxx)
- SETIOS command
- DS8870 R7.4, IOS, DFSMS PTF's





# z/OS (XRC) Global Mirror Workload Based Write Pacing



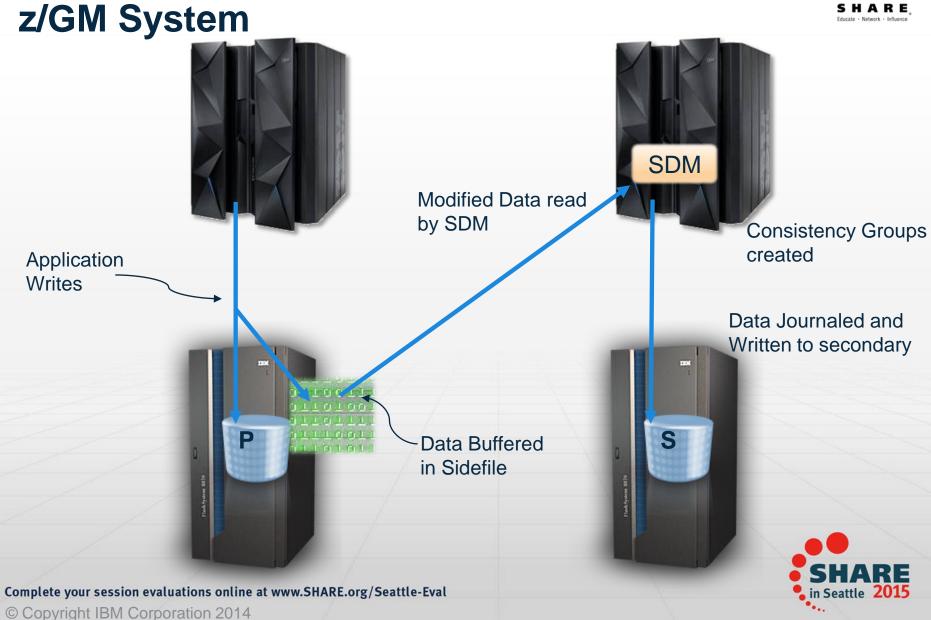


### z/GM (XRC) Workload Based Write Pacing

- Need for Write Pacing
- Current Write Pacing
- Limitations of Current Write Pacing
- Requirements
- Use of Workload Manager (WLM)
- Example
- Implementation Requirements

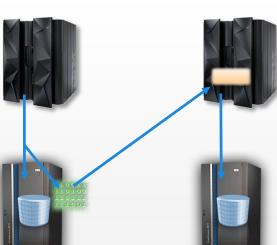






## **Need for Write Pacing**

- Write data is buffered in the DS8000 sidefiles
  - Maximum sidefile size is finite
- Burst write rates can exceed capacity to offload data
  - Sidefiles grow
  - RPO increases
  - Possible suspension if persists
  - Write Pacing monitors sidefile size and injects delays to flatten out peaks of the write rate









### **Previous XRC Write Pacing**

- Volume based
  - Sidefile count monitored for each volume
- Thresholds and Maximum Delay are specified for each volume
  - Different volumes may have different values
- If the sidefile count for a volume grows:
  - Delays injected for writes to that volume
  - Delay starts very small
    - Delay increased if sidefile count increases, up to maximum allowed
    - Delay reduced if sidefile count decreases

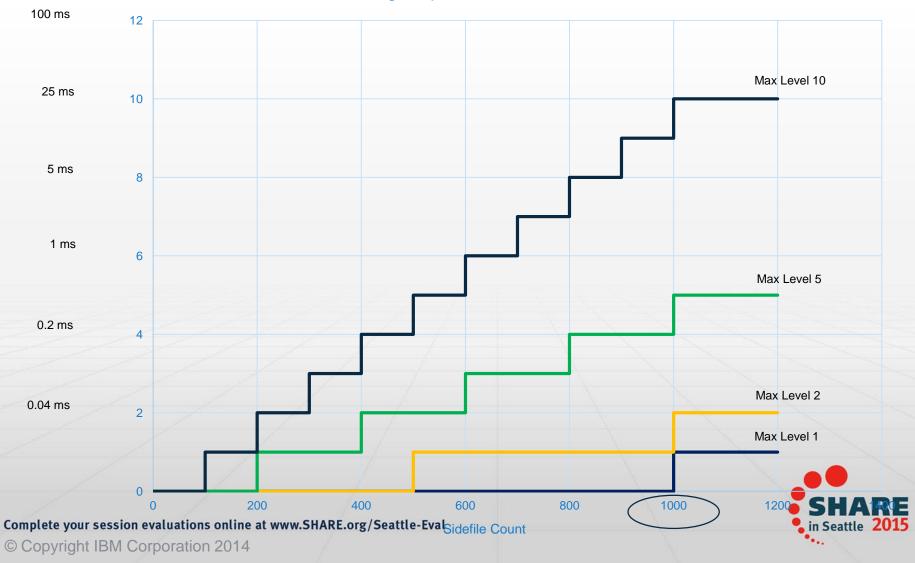




#### Write Pacing Step Function

Delay / Level

Write Pacing Step at Threshold = 1000





### **Limitations to Previous Write Pacing**

- Different applications have different response time requirements
- These requirements are currently met by:
  - Assigning different pacing threshold and limits to different volumes
  - Placing data on volumes with the appropriate pacing levels
  - Requires significant planning for data placement

If requirements change, data must be moved to different volume





#### **Write Pacing Requirements**

- Meet application response time and performance objectives
- Maintain disaster recovery capability within desired Recovery Point Objective (RPO)
- Minimize the amount of manual planning and intervention

Automatically adapt to changing application needs





#### **Workload Manager**

- z/OS Workload Manager (WLM) provides ability to set performance goals
- Applications with similar goals are grouped into Service Classes
- WLM assigns resources to maximize goal achievement
- One part of the resource management is that I/O has an importance value
  - Six importance values:
    - 1 = Highest
    - 5 = Lowest
    - 6 = Discretionary (or default, when not part of a service class)

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#### Workload Based z/GM Write Pacing

- Takes into account the I/O's importance value from WLM when determining the amount of pacing
- Each importance level is mapped to a Maximum Pacing Level
- Pacing levels are set so that higher importance I/O is paced less then lower importance I/O





### **Example with WL Based Pacing**

- Given:
  - Threshold level = 1000
  - Sidefile count = 500
  - Volume Pacing level = 8

Importance Level	Pacing Level	Workload Pacing Delay	Volume Pacing Delay
1 (high)	4	0.04ms	0.2ms
3 (med)	8	0.2ms	0.2ms
5 (low)	12	1.0ms	0.2ms

Delay varies based on I/O's importance





#### **Implementation Requirements**

- Configure WLM
- Define Workload Classes
- Enable IO Priority Management
- Determine maximum delay for each workload class
- Specify these values in the XRC PARMLIB





# Easy Tier Heat Map Transfer



#### Easy Tier Heat Map – With PPRC



- Heat Map maintained at both the primary and the secondary
- But... I/O at the secondary is different from that at the primary

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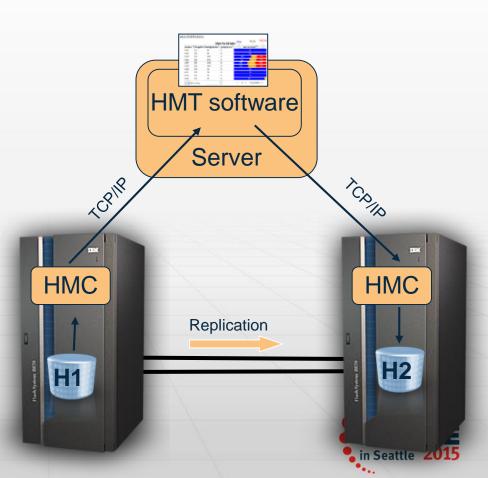
H2

Replication



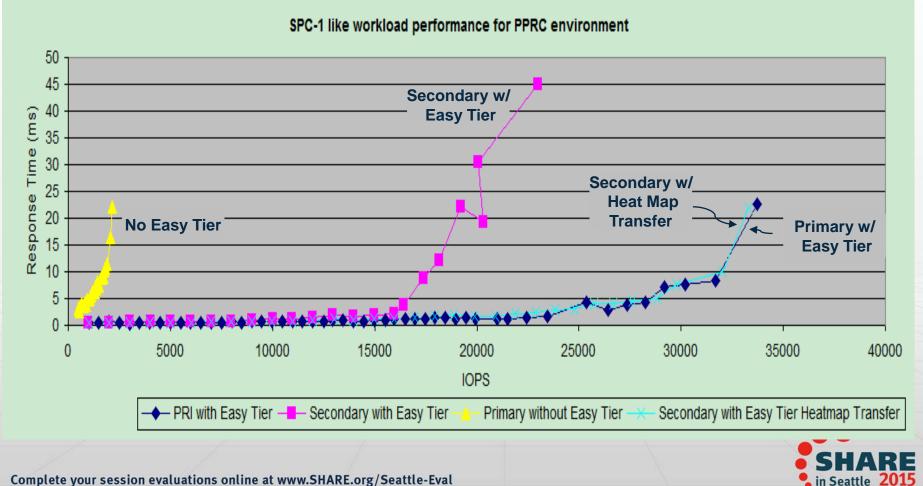
### **Easy Tier Heat Map Transfer**

- Transfers Easy Tier Heat Map information for a volume
- Out of band software implementation
- TPC-R and GDPS support as well as standalone utility





#### **Heat Map Transfer Measurement**



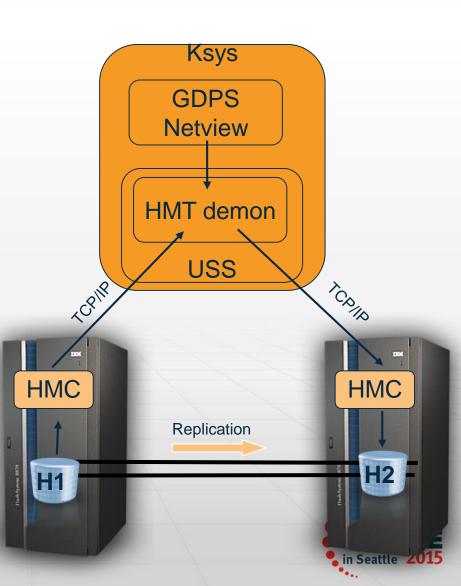
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## **Easy Tier Heat Map Transfer**

- GDPS/PPRC support available in an SPE with GDPS 3.10 and GDPS/GM support available with GDPS 3.11
- GDPS/XRC support is planned to be released next
- 3 and 4 site support planned by combining the different functions





### **Session Summary**

- Replication Overview
- Multiple Incremental FlashCopy
- MultiTarget PPRC Performance
- PPRC Synchronization
- Global Copy Collision Enhancement
- zHyperWrite
- Workload Based z/OS Global Mirror Write Pacing
- Easy Tier Heat Map Transfer

