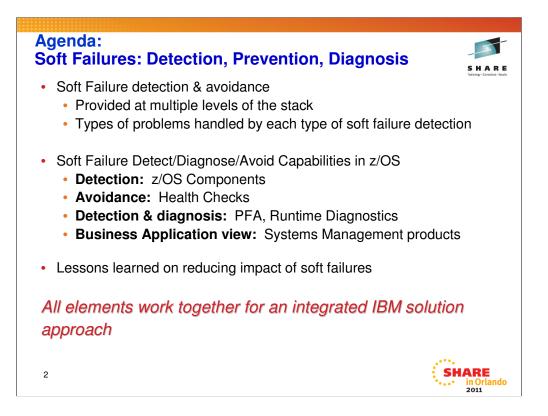


Welcome to this SHARE presentation on z/OS soft failure detection, avoidance and diagnosis.

The goal of this presentation is to show how many parts of the z/OS-based product stack work together to detect, avoid and diagnose Soft Failures.



Up to now, much of what you have heard about soft failure detection has been in the context of Predictive Failure Analysis (PFA).

PFA does a great job predicting problems related to "soft failures", such as growth in resource usage and surfacing rapid error indicators representative of damaged system environments.

However, Soft Failure detection goes beyond PFA ... soft failures have been, and continue to be, detected by base system components; many as a result of problems identified by customers.

Furthermore, many types of soft failures can be avoided by running health checks on a regular basis.

## IBM has actually been working on this problem for a long time, just didn't recognize the unifying theme until recently

PFA covers situations where it is difficult for a component to understand its impact to the system, and where there is no simple component fix.

And Runtime Diagnostics provides an efficient way to diagnose component issues that may result from soft failures, leading to a system that seems "sick but not dead".

This presentation puts these different types of error detection in perspective and shows that IBM has an integrated solution approach where all of the solution elements work together to allow you to identify and react to these types of issues before they impact your system and cause an outage.

What is a soft failure? "Your systems don't break. They just s <i>"Sick, but not dea</i>	stop working and we don't know why."
<ul> <li>Symptoms of a Soft Failure</li> <li>80% of business impact, but only about 20% of the problems</li> </ul>	Manifested as <ul> <li>Stalled / hung processes</li> <li>Single system, sysplex members</li> </ul>
20% of the problems <ul> <li>Long duration</li> <li>Infrequent</li> </ul>	<ul> <li>Single system, syspex members</li> <li>Sympathy Sickness</li> <li>Resource Contention</li> <li>Storage growth</li> </ul>
<ul> <li>Unique</li> <li>Any area of software or hardware</li> </ul>	<ul> <li>CF, CDS growth</li> <li>I/O issues (channel paths, response time)</li> </ul>
<ul><li>Cause creeping failures</li><li>Hard to determine how to isolate</li></ul>	<ul> <li>Repetitive errors</li> <li>Queue growth</li> <li>Configuration</li> </ul>
<ul> <li>Hard to determine how to recover</li> <li>Hard for software to detect internally</li> <li>Brebebilistic pet deterministic</li> </ul>	<ul> <li>SPOF, thresholds, cache structure size, not enabling new features</li> </ul>
<ul> <li>Probabilistic, not deterministic</li> <li>3</li> </ul>	SHARE

#### You can't put your finger on a specific symptom; the system looks alive, but performing poorly.

There are three general categories of software detected system failures: masked failure, hard failure, and failure caused by abnormal behavior. A masked failure is a software detected system failure which is detected by the software and corrected by the software. A hard failure is when the software fails completely, quickly and cleanly. For example, a hard failure occurs when an operating system kills a process.

A system failure caused by abnormal behavior is defined as unexpected, unusual, or abnormal behavior which causes the software solution to not provide the service requested. This abnormal behavior of the software combined with events that usually do not generate failures produce secondary effects that may eventually result in a system failure. These types of failures are known as soft failures.

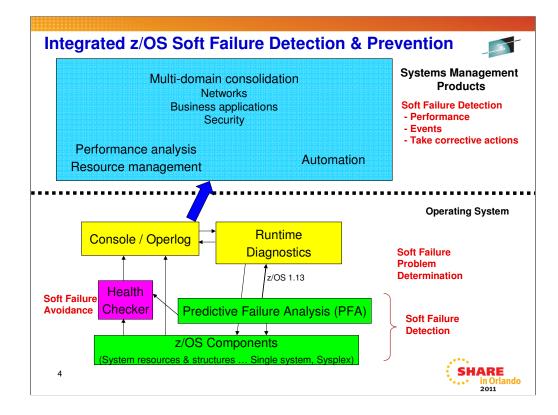
Customers have told us that these soft failures are a small percentage of the problems when compared to masked failures and hard failures, but they cause most of the business impact.

They are hard to diagnose due to the fact that the failure likely does not occur in the address space causing the problem, but more likely occurs in another address space. This sympathy sickness has been observed when either hard failures or abnormal behavior generates a system failure which could not be isolated to a failing component or subcomponent. Failures caused by abnormal behavior often generate sympathy sickness where the problem escalates from a minor problem to the point that the service eventually stops working. Because they are difficult to detect, are very unique, can be triggered anywhere in either software or hardware, and occur infrequently, failure isolation is very difficult.

Hard failures are deterministic in nature. However, a failure caused by soft failures is difficult to recognize within the component and are probabilistic and depend on secondary effects to cause observable damage.

Soft failures tend to manifest themselves in different ways. Configuration issues often appear as:

- Single points of failure
- Cache structures too small
- Log stream thresholds
- Sufficient space for root file system
- Not enabling newer features



This chart shows the collection of components that work together to deliver a solution focused on detecting, avoiding & diagnosing soft failures. We'll discuss each area in sections of this presentation.

•z/OS components

•Health Checks

•PFA & RTD

•Systems management products

PFA is built into the operating system. It is looking for a small number of generic events that could cause a soft failures. It is not looking for events or soft failures in specific address spaces unless they could cause a system crash or hang. PFA is operating system centric in that it works on z/OS. It learns the behavior of the individual behavior and creates predictions for that behavior. It detects soft failures by using complex algorithms imbedded in the component to compare the model behavior for that particular system to the current behavior. PFA is built using remote health check support and provides the information for the soft failure via IBM Health Checker for z/OS which issues the exception to the console (if so configured) as well as the exception and the report data to the health check output in SDSF. From the messages provided by PFA via the health checker support to the console, other products can be used to further analyze the situation.

When PFA detects a system or job with low resource usage, it invokes RTD on behalf of that system or job to determine whether there are factors that could be causing a problem.

In addition, the installation can invoke RTD directly via operator command. In either case, the output of PFA & RTD can be automated on to take further action. In addition, most z/OS management products offer performance analysis and various forms of resource management.

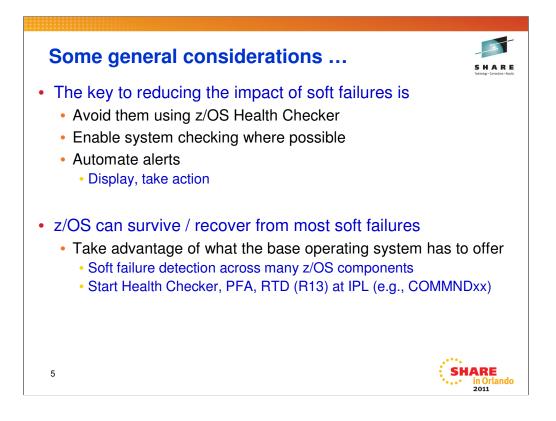
Later in this presentation, we discuss a set of Tivoli systems management products offered by IBM.

The OMEGAMON XE for Management Console will see all health check alerts including the PFA ones. You can build a situation that will alert you if a PFA check is raised and forward that event to other Tivoli event management products (like OMNIBUS or Tivoli Event Console). You can also use Runtime Diagnostics to further analyze PFA results. Runtime Diagnostics provides detailed analysis either the entire system or address space looking for soft failures. It uses lists of messages identified by specific components to review critical messages in the joblog. It also stores information about enqueues to analyze contention, evaluates local lock conditions, and queries a job that has a task in a TCB loop.

Runtime Diagnostics is designed to be used whenever the help desk or operations reports a problem on the system. You should use Runtime Diagnostics to get ready before calling service. Runtime Diagnostics should also be used to help identify the address space causing a PFA exception. PFA identifies a list of potential villains. Runtime Diagnostics can be used to further analyze that address space to detect if it is causing a real problem and to identify what action to take to resolve the problem.

Runtime Diagnostics and Omegamon XE provide additional lower level details than are provided by PFA. The documentation for Runtime Diagnostics as well as PFA can be found in the z/OS Problem Management guide. Starting with z/OS 1.13, PFA calls Runtime Diagnostics to verify abnormally low conditions.

Using customer policy, TSA (via Netview) can detect that a health checker message for PFA exceptions were issued and drive actions.



The key to reducing the impact of soft failures is

•Avoid them using health checker

•Enable system checking where possible

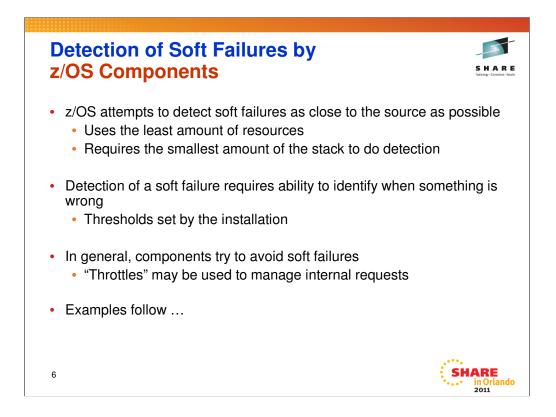
•Alerts can be acted upon. You can display them, automate on them and take action to address the detected problem(s)

It is true that z/OS can survive or recover from many forms of soft failures, as demonstrated by the different types of component checking.

•But you need to take advantage of what the base operating system has to offer; this requires enabling some function parameters, and starting health checker, PFA and RTD during the IPL, such as in the COMMNDxx parmlib member

Most metrics that are used to detect soft failures are very time sensitive, especially when predicting activity based on averages sampled over time.

Predictive trend analysis is not intended to find immediate problems that will bring down a system on a machine-time scale, as the sampling minimum is 1 minute ... 15 minutes for some checks. With some checks (like the ENQ request rate), default collection and comparison every minute; so we could detect something within 2 minutes.



Intro to Component detection of Soft Failures

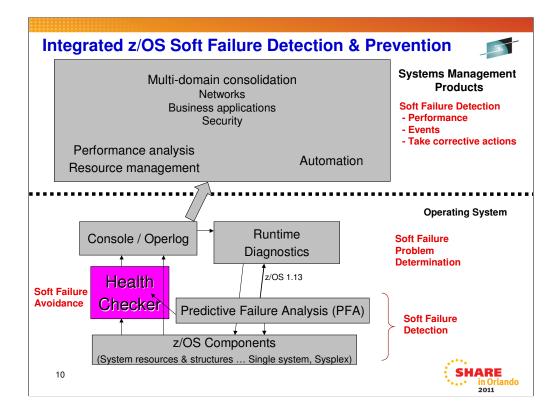
Several examples of component soft failure detection follow on the next set of charts

Whenever possible, components try to avoid soft failures!

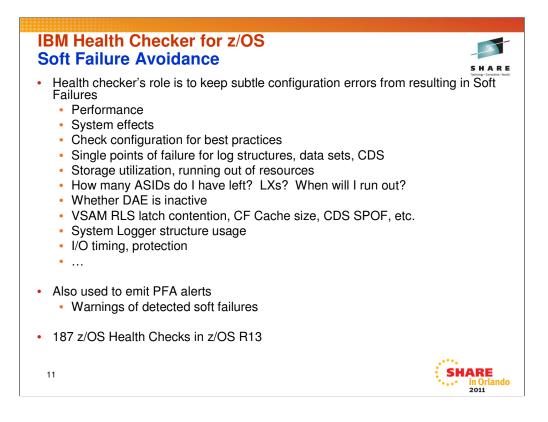
Component	Features	Functions
GRS	Enhanced contention analysis for ENQ, Latch	Identify Blocker/Waiter, Deadly embraces Job name, Creator ASID
	GRS Latch identity string	Associate name with Latch number
	WLM management of blocking units	Prevent deadlocks caused by starvation
	GRS ENF 51	Prevent exhaustion of common storage resulting from GRSQSCAN processing
UNIX System	Latch identity exploitation	Explanations for latch usage on D GRS
Services	XCF communication improvements (R13)	Detected lost messages in sysplex, via message ordering
	System Limits	Checks for buildup of processes, pages or shared storage (process & system level)
	D OMVS,WAITERS to diagnose file system latch contention (enhanced R13: file latch activity)	Identifies holders, waiters, latches, file device numbers, file inode numbers, latch set identifiers, file names, and owning file systems
JES2	JES2 Monitor	Assists in determining why JES2 is not responding to requests "Monitor" msgs issued for conditions that can seriously impact JES2 performance

Component	Features	Functions
IOS	Missing Interrupt Handler	Detection of I/O operations that have not completed within a policy driven time period
	Identify systems sharing a reserve	Identify partner system sharing device
	Captured UCB protection	Prevent accidental overlays of real UCBs in SQA by Legacy applications
	I/O timing facility	Abnormally end I/O requests exceeding I/O timing limits for device; Hyperswap devices as well
	Detect & remove "Flapping Links"	Improved channel recovery (hardware)
	Dynamic Channel Path Management	WLM dynamically move channel paths from one CU to another, in response to workload changes
DFSMS	CAS contention detection	Identify, terminate service tasks beyond a monitored wait time
	VSAM RLS index traps	Checks the structure of all index CIs before writing them to DASD
	Media manager	Recover channel program error retry from I/O errors, using a lower level protocol

Component	Features	Functions
XCF / XES	Stalled member support	Identify unresponsive system, restore to normal operation OR remove it to avoid sympathy sickness
	Exploitation of BCPii to determine dead system more quickly	Avoid waiting the Failure Detection Interval (FDI) if the system is truly dead detect & reset failed system, eliminate data corruption, avoid sympathy sickness.
	Sysplex Failure Management, scenarios	Not updating status, Not sending signals (ISOLATETIME(0): Fencing initiated n seconds after FDI exceeded)
		System updating status, not sending signals (Loss of connectivity: CONNFAIL(YES): remove systems with low weights)
		System Not Updating Status, But IS Sending Signals (SSUMLIMIT(900) length of time system can remain not updating heartbeat (semi-sick), but sending signals)
		Sysplex Member Stalled (MEMSTALLTIME break out of of an XCF signaling jam by removing the largest build- up)
		Take action when connector does not respond, avoiding user hangs (CFSTRHANGTIME)
	Critical Member support; GRS exploitation	If a critical member is "impaired" for long enough, XCF will eventually terminate the member; GRS: remove



Next we'll discuss Health checks, hosted by the z/OS Health Checker



Role of health checker is to avoid subtle configuration error from resulting in Soft Failures

mportant examples						
Component	Health Check	Functions				
XCF	XCF_CDS_SPOF	Evaluates primary & secondary CDS configuration to determine if Sysprog inadvertently created a single point of failure				
	XCF_SFM_SUM_ACTION	Checks ISOLATETIME value, to allow SFM to fence and partition a system without operator intervention and without undue delay.				
	XCF_SFM_SUMLIMIT	Checks status update missing (SUMLIMIT) value				
	XCF_SFM_ACTIVE	Verifies SFM active, policy values				
	XCF_SFM_CFSTRHANGTIME	Verifies CFSTRUCTURE hang time				
	XCF_SFM_CONNFAIL	Threshold for loss of connectivity				
RACF	RACF_GRS_RNL	Evaluates whether the RACF ENQ names are in either the installation system exclusion resource name list (SERNL) or the system inclusion resource name list (SIRNL).				

Details in backup section



Component	Health Check	Functions
Serviceability	DAE_SUPPRESSING	DAE suppresses duplicate SVC dumps so that system resources (processor cycles and dump space) are not used for a dump which provides little or no additional diagnostic value
	SVA_AUTOIPL_DEFINED	Check whether environment can support AUTOIPL, whether active
	SVA_AUTOIPL_DEV_VALIDATION	Validates SADMP, MVS IPL devices
UNIX System Services	USS_PARMLIB	Validate current system against parmlib IPL'd with
		Remind you to update parmlib (due to dynamic changes)
	USS_CLIENT_MOUNTS	With Sysplex, some file systems accessed locally, some of function shipped to the File system owner. Some are accessed locally, but are configured to function ship
	USS_FILESYS_CONFIG	Checks if mount attribute access is read only; whether HFS's in Sysplex root

Details in backup section



### Health Checker: Soft Failure avoidance examples

Component	Health Check	Functions
IOS	IOS_CAPTUCB_PROTECT	UCB capture protection is enabled, allowing UCBs to be temporarily copied to 24-bit storage for legacy software access
	IOS_CMRTIME_MONITOR	Fabric issues have resulted in unacceptable I/O service times
System Logger	IXGLOGR_STRUCTUREFULL	Primary structure full; need to offload
	IXGLOGR_ENTRYTHRESHOLD	High number of entries in element pools
	IXGLOGR_STAGINGDSFULL	Full staging data space

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SHARE in Orlando 2011



Details in backup section

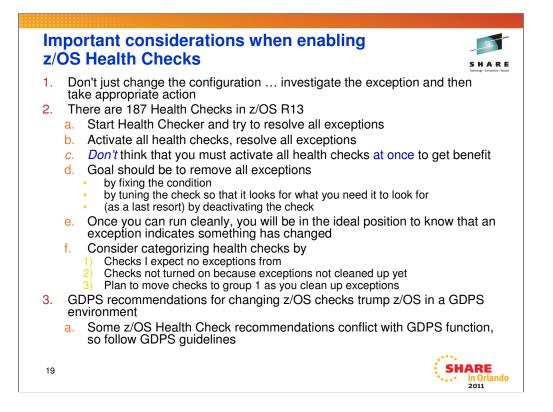
Category	Examples
Detect Single points of failure	VSAMRLS_SINGLE_POINT_FAILURE (SHCDS data sets) XCF_CDS_SPOF (XCF Couple Data Sets) XCF_CF_CONNECTIVITY (CF links, SPOF)
Security	RACF_GRS_RNL (for RACF datasets) SDSF_CLASS_SDSF_ACTIVE (SDSF settings)
Address space checks	IEA_ASIDS (number of ASIDs remaining) IEA_LXS (number of LX's remaining) SUP_LCCA_ABOVE_16M
GRS	GRS_MODE (system configured in STAR mode) GRS_SYNCHRES (GRS synchronous reserve processing enabled) GRS_CONVERT_RESERVES (reserves converted to ENQs)
I/O	IOS_CAPTUCB_PROTECT IOS_CMRTIME_MONITOR (Check for inconsistent average initial command response (CMR)) IOS_MIDAW (MIDAW enabled)

Category	Examples	
Optimal component settings	ALLOC_* (Allocation)	
	CNZ_* (Consoles)	
	CSRES (Comm Server), CSTCP_* (TCP/IP)	
	SDSF_*,	
Sysplex configuration	XCF_*	
	XCF_CF_*	
	CSTCB_*	
	 RRS_*	
	IXGLOGR_*	
	VSAMRLS_*	
	XCF_SFM_*	
	CNZ_*	
	Etc.	

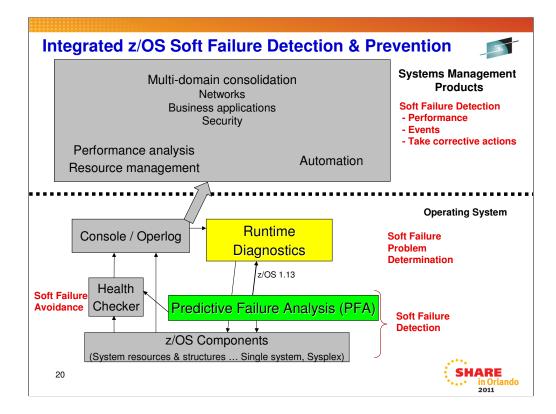
### z/OS Health Check: *Example Categories*

Category	Examples
Serviceability (Dump, Trace	SDUMP_AVAILABLE
options)	SDUMP_AUTO_ALLOCATION (auto-alloc SDUMP data sets)
	CSTCP SYSTCPIP CTRACE (CTRACE active, options)
	CSVTAM_VIT_SIZE (VTAM Internal Trace table size)
	CSVTAM VIT DSPSIZE (VTAM Internal Trace)
	SVA_AUTOIPL_DEFINED
	SVA AUTOIPL DEV VALIDATION
	DAE SHAREDSN
	DAE SUPPESSING
Buffer sizes, storage limits	CSTCP_TCPMAXRCVBUFRSIZE
	CSVTAM_CSM_STG_LIMIT
	VSAMRLS_CFCACHE_MINIMUM_SIZE
	XCF_MAXMSG_NUMBUF_RATIO
	RSM_MEMLIMIT
	RSM_MAXCADS
	RSM_AFQ
	RSM_REAL
	RSM_RSU
	VSM_*

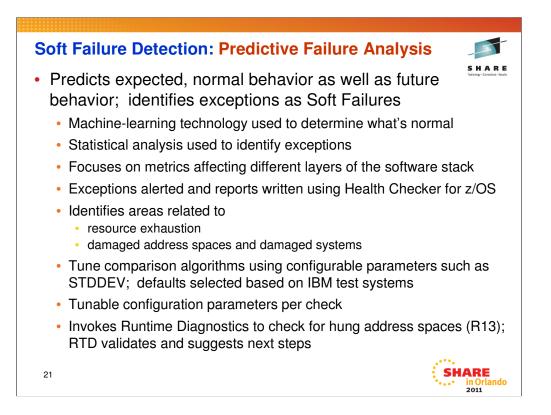
Category	Examples
Hardware	SUP_HIPERDISPATCH (Verify Hiperdispatch enabled) SUP_HiperdispatchCPUConfig (monitors the number of CPUs installed and Hiperdispatch state of the system)
Other component specifics	Console configuration HSM control data set backups JES2 ready to upgrade Reconfiguration SMS CDS configuration System logger Staging data sets full, entry thresholds, structure full USS/ zFS: File system issues VSAM RLS: false contention, monitor contention, monitor unresponsive CICS regions, TVS enabled
Migration checks	



Turn it on. You might find so many exceptions that you feel overwhelmed. But they're all probably things you ought to check out. Since you've been running this way for some time, they're not likely things that you absolutely need to deal with immediately. Your goal should be to get rid of all the exceptions, whether by fixing the condition, or by tuning the check so that it looks for what you need it to look for, or as a last resort by deactivating or even deleting the check. Once you can run cleanly, you will be in the ideal position of knowing that when an exception shows up it is definitely something you want to look at, as something has changed.



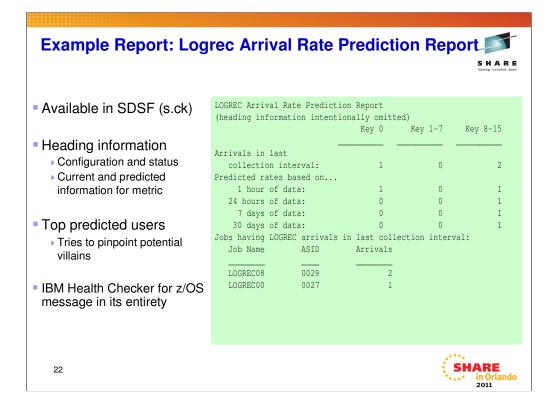
Next, let's transition to the Soft Failure detection & PD segment ... Predictive Failure Analysis (PFA) and Runtime Diagnostics (RTD)



Predict expected, normal behavior based on modeling of past behavior over the past 24 hours, week, month and statistical analysis of current activity.

Tunable algorithms, other parameters

Invokes RTD to check for hung address spaces when PFA considers address space when detection rates are "too low"

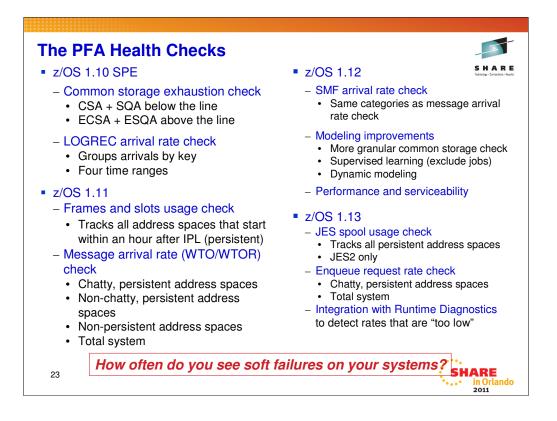


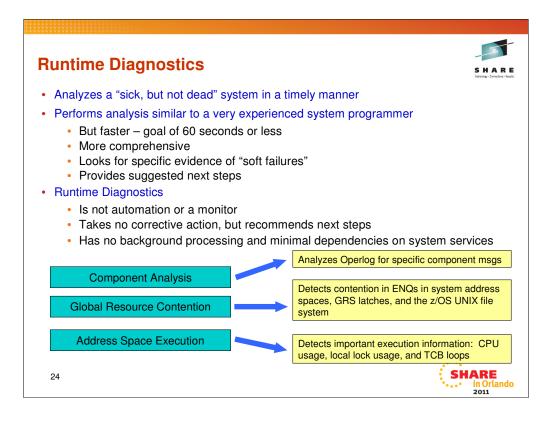
When PFA detects there is no problem, a prediction is produced in the health check option of SDSF. When PFA detects there is a problem, an exception report is printed. All PFA reports are available in SDSF. There is heading information which contains configuration and status for the collections and models.

Each check has its own check-specific information. All checks will display potential villains when an exception occurs. Most of the checks will also list the top address spaces or other important information even when there isn't an exception.

The exception message is configured by default to be issued as a WTO. That message is also included in the exception report along with its detailed response information.

The numbers are in this example are not from a real exception.



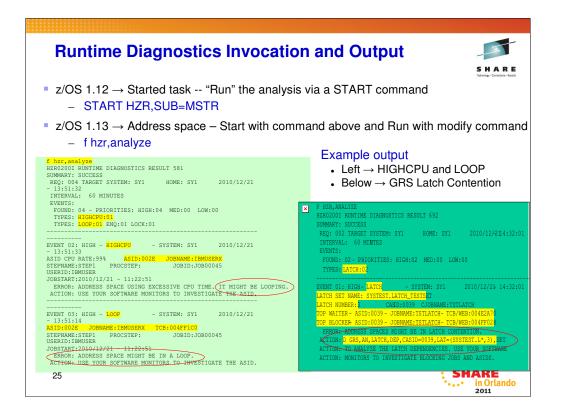


Looking at the operating system only!

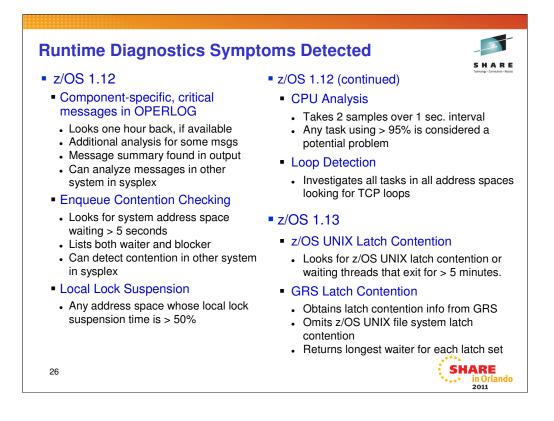
Diagnose sick system by identifying symptoms that could lead to identifying the culprit, and offering next steps to take.

3 areas:

- •Component analysis (messages)
- •Global resources (ENQs)
- Local address space characteristics

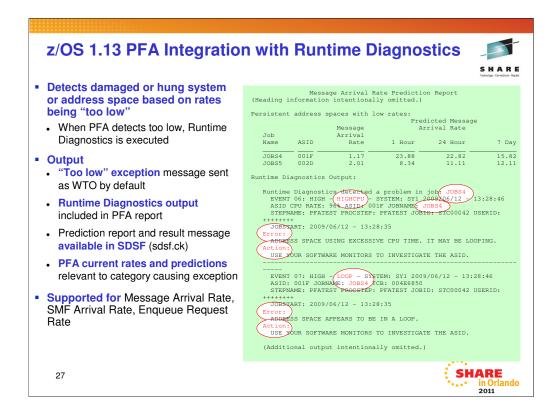


**Loop detection:** Runtime Diagnostics looks through all tasks in all address spaces to determine if a task appears to be looping. Runtime Diagnostics does this by examining various system information for indicators of consistent repetitive activity that typically appears when a task is in a loop. When both a HIGHCPU event and a LOOP event (shown in the example) list the job name, there is a high probability that a task in the job is in a loop. The normal corrective action is to cancel the job name listed.



Use it when getting ready for a bridge call.

**Discreet symptoms** 



When an exception for an abnormally low condition is found, a health check exception will be issued explaining the problem. The PFA report will include the current rates and predicted rates for the category that was failing. In addition it will include the Runtime Diagnostics output received when PFA called Runtime Diagnostics to verify the problem.

Note that in this example, PFA indicated that jobs JOBS4 and JOBS5 had a Message Arrival Rate that was too low when compared to their expected rates for any of the time ranges. Runtime Diagnostics verified that there could be a problem by detecting both a HIGHCPU and a LOOP event for JOBS4. Therefore, the abnormally low message arrival rate coupled with the results of Runtime Diagnostics show that JOBS4 is very likely looping. The Runtime Diagnostics output for JOBS5 were similar, but were purposely omitted from this display due to lack of space.

Just like the other PFA prediction reports, the PFA prediction reports for abnormally low conditions are available in SDSF.



Thus far we have discussed functions in the z/OS stack that perform detection, avoidance and PD for Soft Failures, and exceptions are emitted via WTO messages.

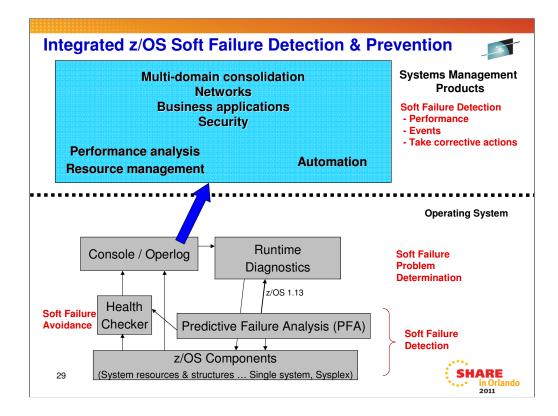
Let's now turn to the Systems Management stack.

Most management stacks provide performance analysis and Resource management, and offer automation of WTO message events to translate the base event to a business action.

In addition, some systems management vendors offer consolidation points for handling OS events, network issues, security, etc.

Tivoli products can integrate a variety of soft failure alert types

- •PFA alerts
- Performance issues
- Other message automation
- •Policy to control corrective actions



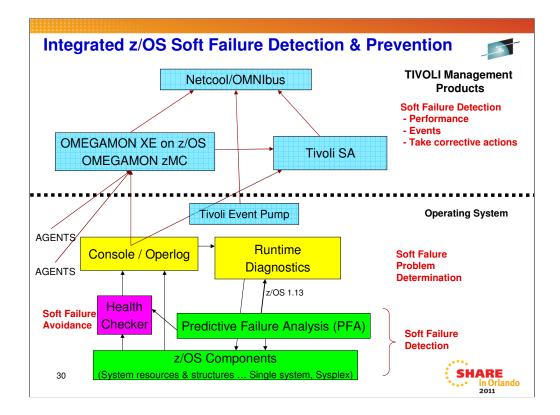
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In addition, some systems management vendors offer consolidation points for handling OS events, network issues, security, etc.

## Transition to next chart ... Systems Management Product box becomes Tivoli products example



Messages provided by PFA via the health checker support, as well as outputs from other health checks and z/OS components, can be used to further analyze the situation.

The OMEGAMON XE for Management Console will see all health check alerts including the PFA ones. You can build a situation that will alert you if a PFA check is raised and forward that event to other Tivoli event management products (like OMNIBUS or Tivoli Event Console). You can also use Runtime Diagnostics to further analyze PFA results. Runtime Diagnostics provides detailed analysis either of either the entire system or address space looking for soft failures. It uses lists of messages identified by specific components to review critical messages in the joblog. It also stores information about enqueues to analyze contention, evaluates local lock conditions, and queries a job that has a task in a TCB loop.

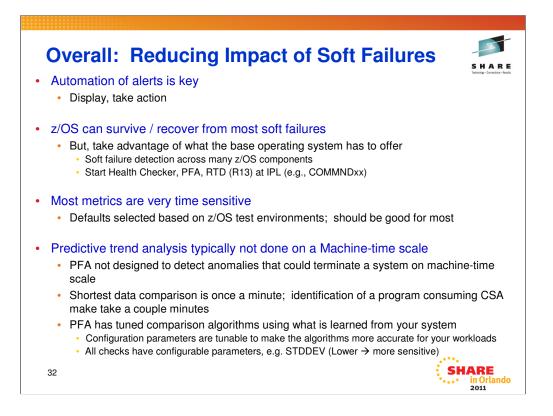
Using customer policy, TSA (via Netview) can detect that a health checker message for PFA exceptions were issued and drive actions.

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Example of Health Check display on the zManagement Console (z/MC)

Exception check counts and counts of how often checks are run are shown in the top half of the screen.

Health check status is shown in the bottom half of the screen image



The key to reducing the impact of soft failures is

·Avoid them using health checker

•Enable system checking where possible

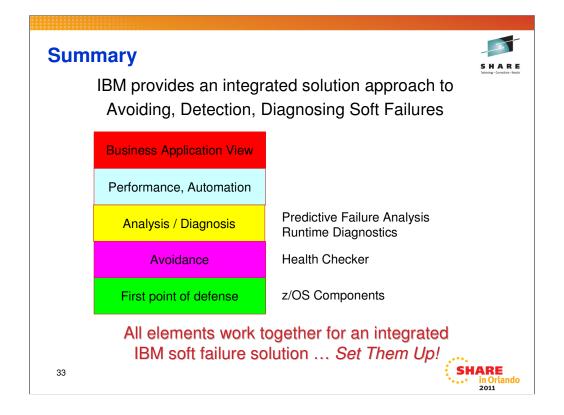
•Alerts can be acted upon. You can display them, automate on them and take action to address the detected problem(s)

It is true that z/OS can survive or recover from many forms of soft failures, as demonstrated by the different types of component checking.

•But you need to take advantage of what the base operating system has to offer; this requires enabling some function parameters, and starting health checker, PFA and RTD during the IPL, such as in the COMMNDxx parmlib member

Most metrics that are used to detect soft failures are very time sensitive, especially when predicting activity based on averages sampled over time.

Predictive trend analysis is not intended to find immediate problems that will bring down a system on a machine-time scale, as the sampling minimum is 1 minute ... 15 minutes for some checks. With some checks (like the ENQ request rate), default collection and comparison every minute; so we could detect something within 2 minutes.



# All of the elements work together for an integrated IBM soft failure solution ... Set Them Up!

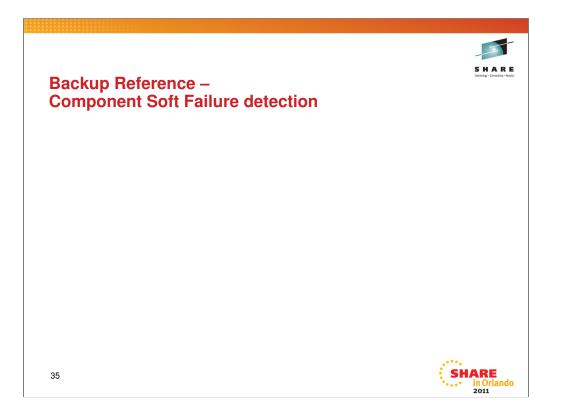
z/OS components Health checks PFA, RTD Systems Management ... Tivoli products

#### Acknowledgements



Thank you to all who contributed information for this presentation

Jim Caffrey	z/OS Predictive Technologies	
Karla Arndt	PFA / RTD	
Scott Bender	USS Kernel	
Ron Bretschneider	DFSMS - Media Manager	
Mark Brooks	XCF, XES, CF	
John Case	USS File System	
Brian Kealy	Omegamon	
Nick Matsakis	GRS, Availability	
Terri Menendez	DFSMS - RLS	
Peter Relson	Health Checker	
Dale Riedy	IOS	
Wayne Rhoten	DFSMS	
Dave Surman	z/OS Architect	
Tom Wasik	JES2	
Doug Zobre	System Logger	SHARE
•		2011



Detection of Soft Failures on a z/OS image:
<ul> <li>Enhanced contention analysis for ENQ / Latch</li> <li>D GRS,ANALYZE,BLOCKER / WAITER / DEPENDENCY</li> <li>D GRS,ANALYZE,LATCH,BLOCKER / WAITER / DEPENDENCY</li> <li>Blocker/Waiter, Deadly embraces, Job name, Creator ASID, etc.</li> </ul>
<ul> <li>GRS Latch identity string</li> <li>Associate name with latch number</li> <li>Included in D GRS latch analysis responses</li> <li>Exploited by USS, RRS, Logger, RACF</li> </ul>
<ul> <li>GRS interacts with WLM to manage priority of blocking units of work</li> <li>Prevent deadlocks causing starvation</li> <li>WLM's "trickle" support ensures that critical work is given cycles gradually to resolve any deadlocks</li> </ul>
<ul> <li>GRS monitor</li> <li>ENF 51 generates blocks in common storage (SQA)</li> <li>SRBs suspended due to stuck receiver (e.g., RMF)         <ul> <li>Therefore too many requests can cause common storage outage</li> <li>GRS piped the requests elsewhere to avoid exhausting common storage</li> </ul> </li> </ul>
• Exploits XCF Critical member support (see XCF critical member support) 36 SHARE

GRS provided enhanced contention analysis to identify ENQ blockers and waiters a number of releases ago,

And recently implemented similar support for latches, also displayed using the D GRS, ANALYZE command.

In R11, GRS delivered the ability to identify latch usage, which is included in the D GRS response. The Latch Identity string is exploited by USS, RRS, Logger and RACF for their latches.

GRS encountered a situation where its ENF 51 events schedule an SRB, which gets suspended due to contention events, keeping its control blocks in common storage. If there are too many requests, SRBs exhaust common storage, causing a system outage.

•The 64 bit SSRBs support helped with the ENF 51 case where the consumer could not keep up with spikes. The suspended SRBs (SSRBs) which were in common could previously exhaust common storage. GRS didn't change to use Pause/Release for this in any way.

•GRS QSCAN/ISGQUERY did change to use Pause/Release rather than schedule a "resume" SRB for its requests as there were cases where the requester space had storage issues which prevented the "resume" SRB from getting it dynamic area in the target address space. This in turn resulted in the QSCAN/ISGQUERY invoker never getting resumed even after the storage issue cleared up. By using Pause/Release, the possibly temporary storage problem was circumvented such that the QSCAN/ISGQUERY invoker was not left hung out to dry.

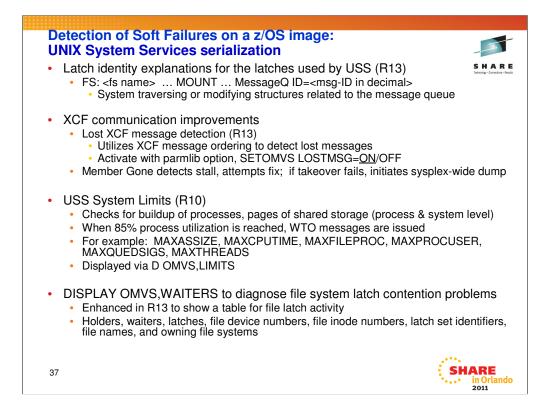
GRS/WLM support to identify ENQs being held by units of work with lower priorities, thus possibly causing deadlocks. Priority is improved to complete processing and release the serialization.

•WLM/SRM added support to identify critical resources, which allows a resource owner to identify a case where a critical resource is blocked by a holder/holders and as such it should take more action to get the holder moving, above and beyond the ENQHOLD/ENQRelease sysevent services that are used. Only DB2 uses this interface.

•WLM introduced the "trickle" support which insures that all dispatchable work, including discretionary, gets some cycles every so often in order to help alleviate serialization bottle necks that were not resolved by ENQHOLD/ENQRELEASE or "critical", or the resource serialization provider did not use the "promotion" services. This is believed to have helped in these types of cases.

Too many XMPOSTs for same ECB

Looks @ ECB to see if already posted & ensure that the post is not done



USS examples

GRS Latch identity service is exploited to identify latch usage for file systems and other latch usage.

Example:

SY2 D GRS, ANALYZE, LATCH, WAITER

SY2 ISG374I 16.15.24 GRS ANALYSIS 734

LONG WAITER ANALYSIS: ENTIRE SYSTEM

----- LONG WAITER #1

WAITTIME JOBNAME E/S CASID LSETNAME/LATCHID

00:01:01 TC0 \*E\* 000E SYS.BPX.A000.FSLIT.FILESYS.LSN

### 20:FS: HOST12.AJAX.DIRECTORY

FS: <fs name>: If the LSETNAME is SYS.BPX.A000.FSLIT.FILESYS.LSN, the latch

is used to serialize operations on the file system named in the latch identity string.

• MOUNT: This latch is used by the file system to serialize operations such as file system mount, unmount, move, and automount and others.

• MessageQ ID=<msg-ID in decimal>: This latch is used when the system is traversing or modifying structures related to the message queue whose identifier is shown in the latch identity string.

Lost XCF message detection ... incurs a performance penalty in high UNIX traffic environments; better reliability

USS built a set of System Limits to identify storage creep

Dynamic socket limit

Detection of Soft Failures on a z/OS image: IOS examples
<ul> <li>Missing Interrupt Handler</li> <li>Incomplete I/O: Prevents an application or system outage due to an error in any one of the following places: <ul> <li>Device</li> <li>Control Unit</li> <li>Fabric</li> <li>Operator/CE error (IML, cable pulls, etc)</li> </ul> </li> <li>Outage is prevented by: <ul> <li>Detecting when an I/O operation has not completed within a policy driven time period</li> <li>Invoking system diagnostic routines to understand the scope of the error</li> <li>Driving hardware and software recovery mechanisms</li> <li>First Failure Data Capture</li> </ul> </li> </ul>
<ul> <li>Identify sharing systems holding a reserve</li> <li>Start-pending MIH condition → D U,VOL= to identify device number</li> <li>D GRS,DEV=dddd to determine reserve status</li> <li>Identify other system with reserve, in message (IOS431I device reserve to CPU)</li> </ul>
Captured UCB protection <ul> <li>Creates a temporary copy of UCBs for Legacy applications</li> <li>Prevents accidental overlays of real UCBs in SQA</li> </ul> 38

MIH intercepts incomplete I/O operations to prevent an application or system outage due to a device, control unit, fabric or hardware (cabling) error.

Once the scope of the problem is understood, hardware & software recovery mechanisms are invoked and diagnostic data is captured.

Identify sharing systems holding a reserve: IOS071I dddd,\*\*,jobname, START PENDING

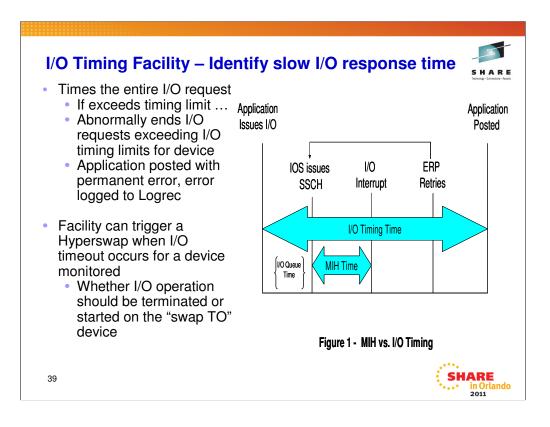
Normally, due to a reserve being held on another system

On Sharing systems

Use D U,VOL=volser to identify device number Use D GRS,DEV=dddd to identify reserve status

IOS4311 will identify systems holding reserves IOS4311 DEVICE dddd RESERVED TO CPU=serialmodn,LPAR ID=ii SYSTEM=sysname

Captured UCB protection ... prevent Legacy components from impacting IOS by modifying the UCB; Solution for 24-bit programs



The system invokes the <u>I/O timing facility</u> to monitor I/O requests. If an active I/O request has exceeded the I/O timing limit, the system abnormally ends the request and does the following:

•Clears the subchannel of all active, start pending, or halt pending I/O requests.

·Issues a message to the system operator.

•Obtains information about the terminated request (such as whether the request was queued or started) to build an MIH record.

If a queued I/O request has exceeded the I/O timing limit, the system abnormally ends the request and does the following:

Issues a message to the system hardcopy log

•Obtains information about the terminated request (such as whether the request was queued or started) to build an MIH record.

The <u>I/O timing facility</u> can be enabled to trigger a HyperSwap when an I/O timeout occurs for a device that is monitored for HyperSwap. Optionally, the user can specify whether a timed-out I/O operation that initiates a HyperSwap is to be terminated or allowed to be started on the swap 'TO' device.

For any I/O requests that exceeds the I/O timing limit, the system performs the following actions:

When the I/O timing trigger is not enabled for HyperSwap, or is enabled and the IOTTERM option is also enabled:

•Abnormally ends the I/O request that has exceeded the time limit, and does not requeue the request for execution.

•Issues a message.

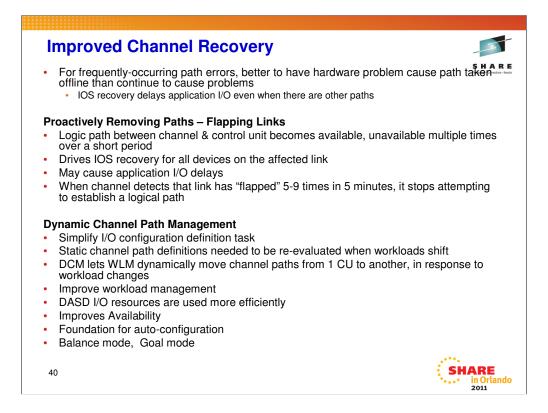
•Writes an entry in the SYS1.LOGREC data set for the abnormally ended I/O request.

When the I/O timing trigger is enabled for HyperSwap and the IOTTERM option is disabled:

•Abnormally ends the I/O request that has exceeded the time limit, and requeues the request for later execution on the swap 'TO' device at the completion of the HyperSwap.

•Issues a message for the first timeout condition that triggers a HyperSwap on the associated DASD subsystem.

•Writes an entry in the SYS1.LOGREC data set for the abnormally ended I/O request.



Customers have said that when errors occur frequently enough on a path that they would rather see the path taken offline rather than having the hardware or z/OS repeatedly try to recovery the path. An example where support was added is the flapping links support that was introduced in the z9 processor. Flapping links is a condition where the logical path between the channel and control unit becomes available and unavailable (e.g., loss of light) multiple times within a short period of time. This causes IOS recovery processing to be initiated multiple times for all devices on the affected link, which may delay application I/O for long periods of time, even though there are other paths available. When the channel detects that the link has "flapped" 5-9 times in 5 minutes, it stops attempting to establish a logical path.

In addition, customers have also said that they'd like to see z/OS be more proactive about removing failing paths from devices. That is, instead of waiting for each device to trip over the error and take the required recovery action, they'd like to see z/OS remove the path from all devices in an LCU when an error causes the path to be removed from the first device. This will significantly reduce recovery time and improve application performance when an error occurs.

#### Dynamic Channel Path management

Prior to Dynamic Channel Path Management, all channel paths to I/O control units had to be statically defined. In the event of a significant shift in workload, the channel path definitions would have to be reevaluated, manually updated via HCD, and activated or POR'ed into the configuration. Dynamic Channel Path Management lets Workload Management dynamically move channel paths through the ESCON Director from one I/O control unit to another, in response to changes in the workload requirements. By defining a number of channel paths as "managed," they become eligible for this dynamic assignment. By moving more bandwidth to the important work that needs it, your DASD I/O resources are used more efficiently. This may decrease the number of channel paths you need in the first place, and could improve availability -- in the event of a hardware failure, another channel could be dynamically moved over to handle the work requests.

Dynamic Channel Path Management operates in two modes: balance mode and goal mode. In balance mode, Dynamic Channel Path Management will attempt to equalize performance across all of the managed control units. In goal mode, which is available only when WLM is operating in goal mode on all systems in an LPAR cluster, WLM will still attempt to equalize performance, as in balance mode. In addition, when work is failing to meet its performance goals due to I/O delays, WLM will take additional steps to manage the channel bandwidth accordingly, so that important work meets its goals.

Detection of Soft Failures on a z/OS image:	
DFSMS examples	
CAS Contention Detection	SHARE Technology - Connections - Results
<ul> <li>Runs as part of the CAS analysis task</li> </ul>	
<ul> <li>Periodically checks the Catalog Address Space (CAS) so (every 30 seconds or upon request)</li> </ul>	
<ul> <li>Based on a set wait time and reason class, determines thos beyond the wait time.</li> </ul>	
<ul> <li>Checks for service tasks that are active and waiting on the SYSZ timer for each waiting task (10 min)</li> </ul>	TIOT enqueue. It sets
<ul> <li>Creates a symptom record for each task past the limit</li> </ul>	
<ul> <li>Terminates some of the violating tasks, which were consider terminate</li> </ul>	red safe to
VSAM RLS index traps	
<ul> <li>Set the trap using a V SMS,MONDS command</li> </ul>	
Checks the structure of all index CIs before writing them	to DASD.
<ul> <li>If problem, abend is issued and write is avoided</li> </ul>	
Media Manager	
<ul> <li>Channel program error retry from I/O errors, using a lowe supported by the device</li> </ul>	er level protocol
zHPF transport mode channel program	
Command mode channel program with MDAWs     Command mode channel program with IDAWs	
Command mode channel program with IDAWs     Mode Manager will retry the I/O with one of the lower law	vol protocolo
<ul> <li>Media Manager will retry the I/O with one of the lower lev</li> </ul>	SHARE
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#### Catalog contention detection

•The possibility exists that while catalog service tasks are waiting on an event, the event may not finish or complete. It could take the event an unreasonably long time to return, leaving the Catalog Address Space (CAS) service task waiting, possibly indefinitely. Contention support identifies those CAS tasks which appear to be stuck while waiting on an event. When these tasks are identified as having passed a threshold, in all cases, a symptom record will be created. Some CAS tasks past the threshold, which are identified as reasonably safe to terminate, are terminated, freeing the available CAS service task for additional work. The wait threshold is initially based on a time defaulted by the system (30 minutes). The wait threshold is also user selectable with a minimal wait-time of 30 minutes.

### VSAM RLS index traps

•Set the trap via a VARY SMS "monitor data set" command (V SMS,MONDS(IGWVSAM.BASE.INDEX.TRAP),ON )

VSAM checks index Control Intervals for problems

### Media Manager

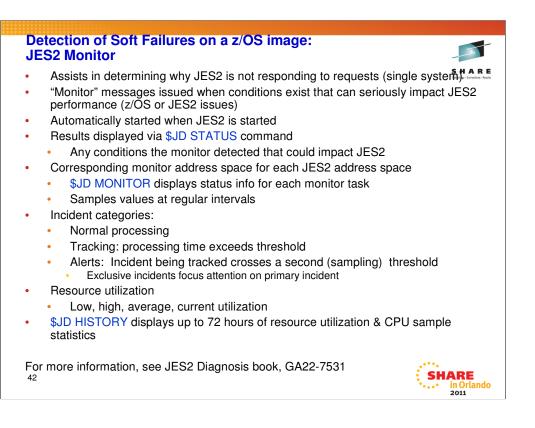
Channel program error retry from I/O errors, using a lower level protocol supported by the device

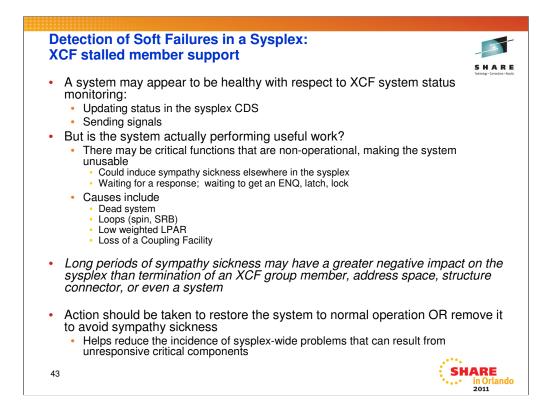
•zHPF transport mode channel program

•Command mode channel program with MIDAWs

•Command mode channel program with IDAWs

•Media Manager will retry the I/O with one of the lower level protocols



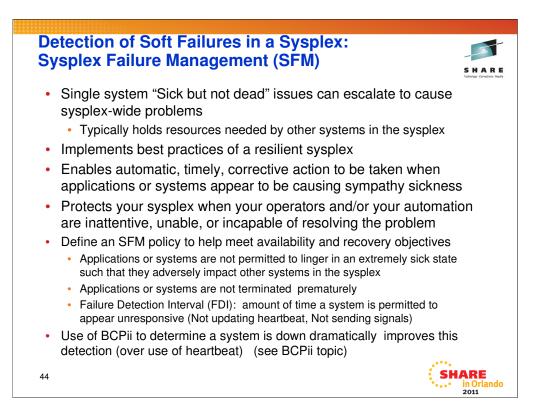


# XCF and Sysplex sympathy sickness

Intro to XCF/SFM support for termination of stalled XCF group members, related to avoiding sympathy sickness.

Many of the issues detected by XCF & SFM are causes of soft fialures ... stalled members, underlying system issues. The stall of an XCF group member is often the result of some single or cascaded set of problems that will ultimately affect the ability of the sysplex to service business applications.

To present these types of soft failures, action should be taken to restore the impacted system to normal operation OR remove it to avoid sympathy sickness.



SFM deals with the detection and resolution of soft failures that could cause sympathy sickness conditions when a system or sysplex application is unresponsive.

Single-system "sick but not dead" issues can and do escalate to cause sysplex-wide problems.

A sick system typically holds resources needed by other systems a unable to participate in sysplex wide processes

Thus other systems become impacted.

Root cause of the sickness is a single system problem ... contention, dispatching delays, spin loops, overlays, queue/data corruption, etc.

(These are soft failure symptoms as well.)

Routing work away from the troubled system does not necessarily guarantee that other systems will not be impacted.

However, allowing non-terminating problems, where something simply becomes unresponsive, to persist *typically compounds the problem*.

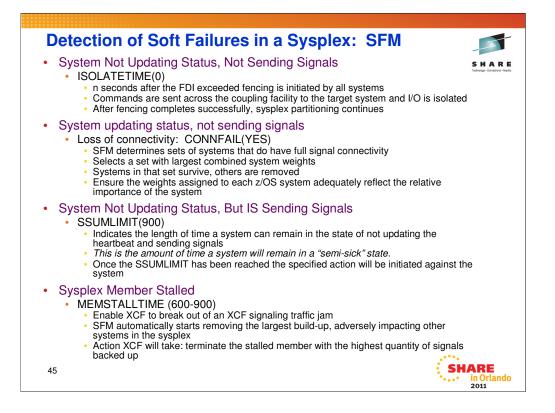
By the time manual intervention is attempted, it is often very difficult to identify the appropriate corrective action.

Appropriate SFM specifications enable systems in the sysplex to take corrective action automatically.

In general, each parameter arises out of real world situation that led to some sort of (usually quite ugly) outage.

The next few charts outline features that are important to detecting soft failure situations related to cluster processing.

XCF\_SFM\_ACTIVE health check



XCF\_FDI health check XCF\_SFM\_SUM\_ACTION health check XCF\_SFM\_SSUMLIMIT health check

#### FDI = Failure Detection Interval (XCF)

•Amount of time a system is permitted to appear unresponsive (not updating heartbeat, not sending signals) •If the specified FDI value is too short, it might trigger unnecessary actions by SFM;

•If FDI is set too long, it could elongate the detection window for soft failures related to sympathy sickness

•It's best to let FDI default to being based on internal "spin time" (rather than specifying it as a "user FDI" value) This chart outlines a number of common sysplex customer situations detected by SFM.

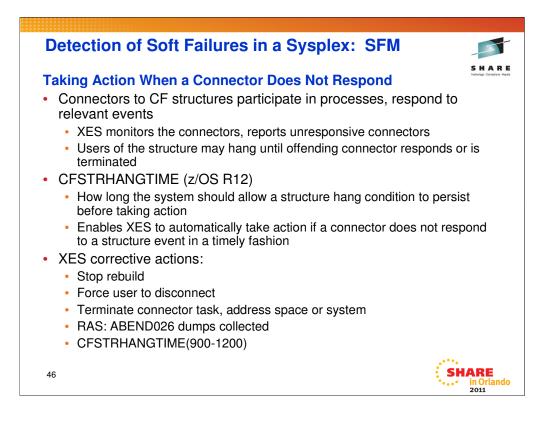
MEMSTALLTIME enables system to break out of an XCF signaling traffic jam. SFM will automatically start removing the largest build up. In the picture above, imagine all the blue cars were instantly removed.

(SSUM = Status Update Missing condition) ... SSUMLIMIT(#seconds)

When you have specified or defaulted to SSUMLIMIT(NONE), and a system has not updated its status within the failure detection interval but continues to produce XCF signaling traffic, SFM prompts the operator to optionally force the removal of the system. The fact that XCF signalling continues indicates that the system is functional but may be experiencing a temporary condition that does not allow the system to update its status. If the operator decides that removal of the system is necessary, message IXC426D provides the prompt to isolate the system and remove it from the sysplex. In this case, the ISOLATETIME interval specified in the SFM policy is ignored.

If XCF signaling also stops, SFM will start to isolate the failing system at the expiration of the ISOLATETIME interval. With a value other than none specified for the SSUMLIMIT SFM administrative data utility parameter, SFM will start to isolate the system when the time specified for the SSUMLIMIT parameter has expired for a system that is in status update missing condition but still producing XCF signalling traffic.

If the system stops producing XCF signalling traffic, SFM may start to isolate the failing system before the SSUMLIMIT time expires, at the expiration of the ISOLATETIME interval.



Connectors to CF structures need to participate in various processes and respond to relevant events XES monitors the connectors to ensure that they are responding in a timely fashion

If not, XES issues messages (IXL040E or IXL041E) to report the unresponsive connector (outstanding responses)

Users of the structure may hang until the offending connector responds or is terminated

Installations often fail to react to these messages, or worse, react by terminating the wrong connector

CFSTRHANGTIME indicates how long the system should allow a structure hang condition to persist before taking corrective action(s) to remedy the situation

Corrective actions may include:

Stopping rebuild

Forcing the user to disconnect

Terminating the connector task, address space, or system

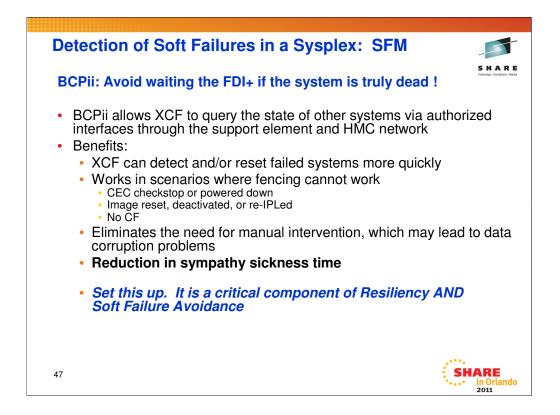
Each system acts upon its own connectors

IXL040E CONNECTOR NAME: connector-name, JOBNAME: jobname, ASID: asid HAS *text. process* FOR STRUCTURE *structure-name* CANNOT CONTINUE. | MONITORING FOR RESPONSE STARTED: *mondate montime*. DIAG: *x* 

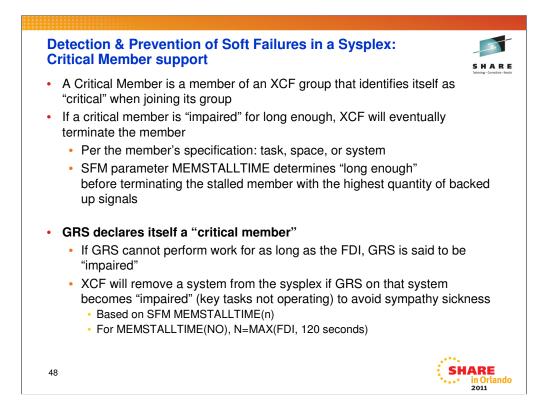
IXL049E HANG RESOLUTION ACTION FOR CONNECTOR NAME: *conname* TO STRUCTURE | *strname*, JOBNAME: *jobname*, ASID: *asid*: *actiontext* 

IXL041E CONNECTOR NAME: connector-name, JOBNAME: jobname, ASID: asid HAS NOT RESPONDED TO THE event FOR SUBJECT CONNECTION: subject-connector-name. process FOR STRUCTURE structure-name | CANNOT CONTINUE. MONITORING FOR RESPONSE STARTED: mondate | montime. DIAG: x

IXL050I CONNECTOR NAME: conname TO STRUCTURE strname, JOBNAME: jobname, | ASID: asid HAS NOT PROVIDED A REQUIRED RESPONSE AFTER | noresponsetime SECONDS. TERMINATING termtarget TO RELIEVE THE | HANG.



SFM will automatically exploit BCPii and as soon as the required configuration is established. (a) Pairs of systems running z/OS 1.11 or higher (b) BCPii configured, installed, and available (c) XCF has security authorization to access BCPii defined FACILITY class resources (d) z10 GA2 with appropriate MCL's, or z196 (e) New version of the sypslex CDS is primary in the sysplex (f) toleration APAR OA26037 for z/OS 1.9 & 1.10 (g) SYSSTATE DETECT function is not enabled.



Critical member is a member (component) of an XCF group identified to be "critical"

If GRS cannot perform its work for as long as the failure interval, it is marked "impaired"; GRS indicated that it is to be removed from the sysplex to avoid sympathy sickness. The monitoring includes work queues, units of working being able to be dispatched, and XCF messages that appears hung due to GRS not processing messages. The messaging support also include GRS STAR lock structure signal required for contention management.

## SFM MEMSTALLTIME

MEMSTALLTIME enables the system to break out of an XCF signalling jam; specifies action XCF will take: terminate the stalled member with the highest quantity of signals backed up

"Back stop" to allow the system to take automatic action to alleviate a problem if it cannot be resolved in a timely manner



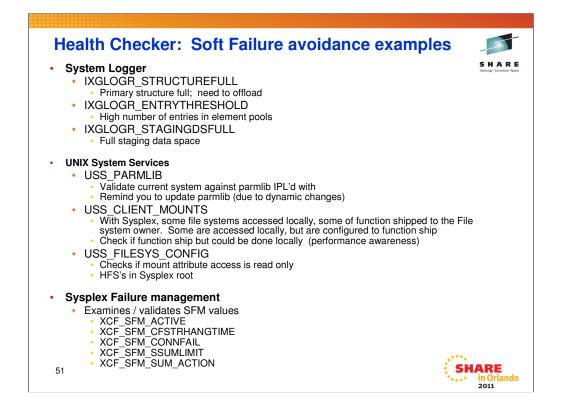
Health Checker: Soft Failure avoidance examples
<ul> <li>DAE_SUPPRESSING</li> <li>DAE suppresses duplicate SVC dumps so that system resources (processor cycles and dump space) are not used for a dump which provides little or no additional diagnostic value</li> <li>IBM recommendation is to activate this function.</li> <li>If turned off, then health checker will issue an exception to alert the team to this sub optimal configuration.</li> </ul>
<ul> <li>XCF_CDS_SPOF</li> <li>z/OS uses two coupling data sets (CDS) to manage a parallel sysplex, primary and alternative.</li> <li>This check evaluates the I/O configuration to determine if the I/O configuration has inadvertently created a single point of failure (SPOF) when accessing the data on the primary and alternative CDS.</li> <li>Alternative CDS created to handle a problem with a switch or a storage device.</li> </ul>
<ul> <li>SVA_AUTOIPL_DEFINED, SVA_AUTOIPL_DEV_VALIDATION</li> <li>Check whether environment can support AUTOIPL, whether active</li> <li>Validates SADMP, MVS IPL devices</li> </ul>
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Examples of Soft Failure avoidance

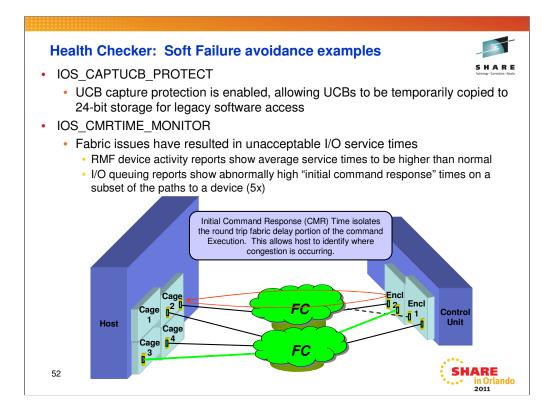
•DAE

•CDS Single points of failure

AutoIPL defined and valid DASD devices specified for Stand Alone Dump & MVS IPLs



Examples of Soft Failure avoidance

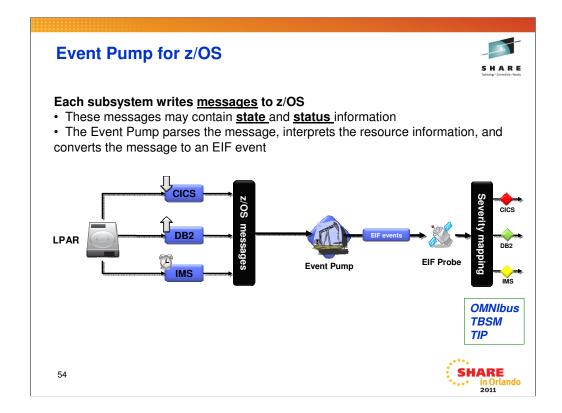


Examples of Soft Failure avoidance

IOS Captured UCB protection verifies that Captured UCB protection is enabled on this system. This allows UCBs to be temporarily copied to 24-bit addressable storage to allow access by Legacy software in the first 16 Mb of storage. This ensures that legacy software cannot interfere with the state of the devices

CMR time monitor detects if any control units in the system are reporting inconsistent average initial "command response" (CMR) time for their attached channel paths. An exception is raised if at least one control unit in the system has a path with an average CMR time that is highest among the other paths to the control unit, greater than a specified thresholds.





Event Pump is a fairly new z/OS agent that extracts information based on messages, System Automation events, Netview PPI, Health Checker ... and represents the events in terms of state & status, via EIF (event information FW).

EIF (Event Integration Facility) communicates with other (distributed) Tivoli products, as well as other vendor products.